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Considering the consistency constraint, the previous  $n$  steps are mapped into  $m$  intermediate tensors  $\sim H(t, o)$  by  $f(J, K, \cdot)$  in Equation (3) at first, where  $K$  and  $J$  are 3D convolutional kernels. Note that  $f(J, K, \cdot)$  is a mapping function with dynamic physics constraints, which will be discussed in Section 3.3.

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